

# **INMARSAT Pilot Receiver**

Model RCV-INMST



This receiver makes use of digital signal processing techniques to track a CW pilot signal. A phase continuous, 1 Hz step size, frequency synthesizer generates an error correction signal which is used in conjunction with MITEQ's INMARSAT AFC capable frequency converters to provide Automatic Frequency Control for both maritime and aeronautical (Enhanced AFC) applications.

## Features

- Enhanced AFC operation
- Low noise/low spurious output
- Tunable input (5 kHz step size)
- Extensive remote capability (RS485)
- Large graphic display
- Simple setup

# **Options**

- Higher output level
- 50 ohm IF impedance
- 10 MHz reference frequency
- · Remote RS422, RS232, or IEEE-488 interface



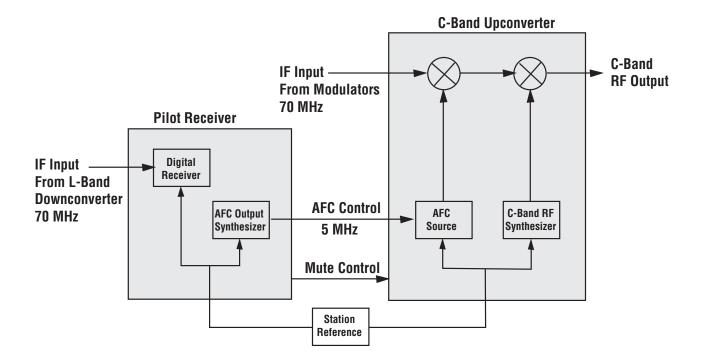


Specifications	
Input characteristics	
Frequency	50-90 MHz tunable in 5 kHz steps
Level	-50 to 0 dBm
Return loss	20 dB nominal
Impedance	75 ohms (50 ohms optional)
Output characteristics	, ,
Frequency	5 MHz
Level	0 ±3 dBm (+10 dBm optional)
Return loss	20 dB nominal
Impedance	50 ohms
Tracking ratio	-1:1 (other ratios optional)
Frequency correction	INMARSAT Aero
Frequency step size	1 Hz minimum,
	10 Hz maximum
Frequency rate of change	15 Hz/second maximum
Phase during frequency step	Phase continuous
Spurious	-70 dBc, 10 Hz to 10 kHz,
	-65 dBc, 10 kHz at 1 MHz
Phase noise	-80 dBc/Hz at 10 Hz,
	-90 dBc/Hz at 100 Hz,
	-100 dBc/Hz at 3 kHz
Residual noise from the input	No residual noise from the input
Monitor port	-20 dBc nominal
Acquisition/tracking characteristics	
Pilot type	CW
Frequency range	±50 kHz
Frequency rate of change	±1 kHz/minute
Carrier-to-noise ratio	40 dB (38 dB typical) for acquisition,
	40 dB (30 dB typical) for tracking
Acquisition time	15 seconds typical
Adjacent channel rejection	Modulated carriers may be +10 dBc
Pilot loss/hold time	A lost pilot is indicated on the front panel,
	After 1 hour of continuously lost pilot, a mute
	command is issued via a rear panel contact closure,
	A lost pilot does not interrupt the output signal,
	Pilot reacquisition occurs during the hold time
Loop bandwidth	Not applicable – see Technical Note 25T021
Reference characteristics	
Frequency	5 MHz (10 MHz optional)
Level	0 ±3 dBm
Impedance	50 ohms

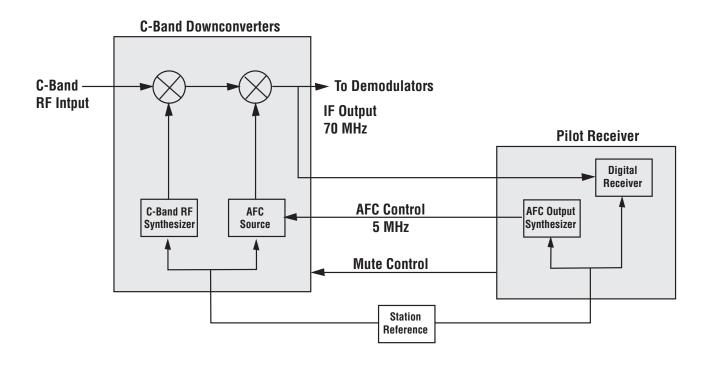
# **Options**

- **11.** Increased output power: +10 dBm.
- **15.** 50 ohm IF impedance.
- **17.** Remote control.
  - **A.** RS422.
  - **B.** RS485 (supplied as standard).
  - C. RS232.
  - **F.** IEEE-488.
- **24.** 10 MHz reference frequency.

## **INMARSAT C-Band AFC Upconverter Subsystem, Simplified Block Diagram**



# **INMARSAT C-Band AFC Downconverter Subsystem, Simplified Block Diagram**



## **General Specifications**

### **Primary Power**

#### **Summary Alarm**

Contact closure/open for DC voltage and/or component alarm

#### **Converter Mute Control**

Contact closure/open for mute/unmute of RF converters

### **Physical**

(chassis depth 20" [508mm])

Rear panel connectors

IF inputBNC femaleAFC outputBNC femaleAFC output monitorSMA femaleReference inputBNC female

Remote interface...... DEM-9S for RS485 and RS422,

DB-25P for RS232,

IEEE-488 receptacle for GPIB

### **Environmental**

Operating

Ambient temperature ..... -50 to +70°C
Relative humidity....... Up to 95% at 40°C
Atmospheric pressure ...... Up to 40,000 feet

Shock and vibration ...... Normal handling by commercial carriers

#### **Technical Notes**

25T020 Enhanced Automatic Frequency Control for INMARSAT Earth Stations 25T021 Phase-Locked Vs Digital Pilot Receivers: Pilot Receiver Loop Bandwidth 25T023 Local/Remote Control Description of INMARSAT Receiver

